# OSD Mantech P 2 Automated Repair Cell - ARC

Presented by: Lawrence Binek

OSD Mantech Program Office managed by ARL under contract Cooperative Agreement Number W911NF-10-2-0094 with UTRC.





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### **Contractor Team Members**



#### Contracting & Technical Lead

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# United Technologies Research Center

#### Helium Recovery Support

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#### Roles:

#### H-60

- Component Engineering
- Requirements Development
- Qualification Engineering
- Sump supplier



#### **United Technologies Research Center**

# antum Technology Corp.

#### Helium Recovery System

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#### **Equipment Support**

Dr Christian Widener VRC Metal Systems Ph 605-716-0062



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Role: Automation & motion syst.



#### **Transition Support**

Bob Bierk Integrated Support Services Moog Inc. Ph: 716-352-0951 rbierk@moog.com

#### Roles:

Cold Spray Production

- CS Equipment Supplier
- Production Facilities
- Qualification Operations

### **Presentation Overview**

### Automated Repair Cell process overview

### Current design status

Alternate configurations

### Sub-component selection

- 5-Axis machining center
- Main sealed chamber
- Helium Reclamation system
- Automation



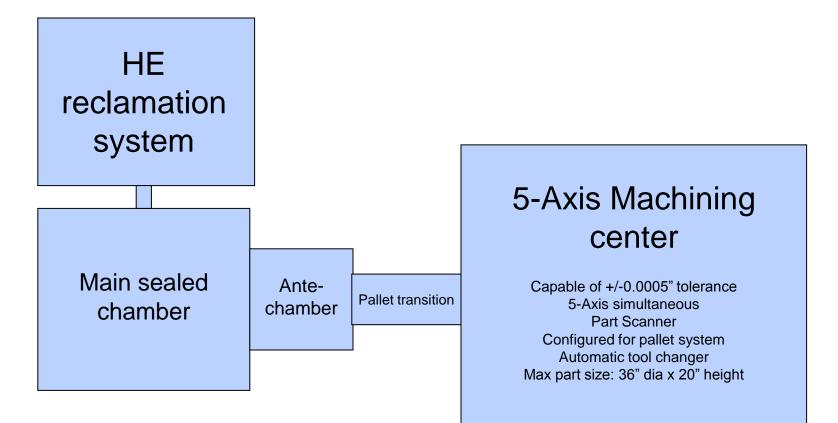
### ARC – Automated Repair Cell Process review

- Repair damaged hardware
  - Advanced machining capability
  - Cold Spray additive deposition
- Incorporate scanning technologies
  - Compare damaged hardware to nominal solid mode
- Multi-phase automated cycle from hardware insertion to removal



### ARC – Current Design status

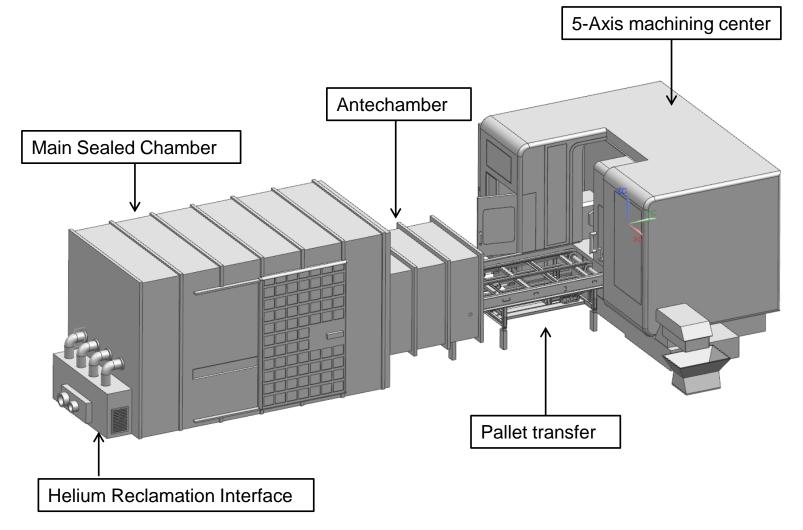
#### System level overview





## ARC – Current Design status

#### Preliminary concept





### Alternate configurations

Task dependent functionality

- ARC machining capability scaled for work function.
  - Bridge mill can facilitate oversized components.
  - Main sealed chamber can be used as a "stand-alone" section with cold spray and light machining conducted by robot.
    - Periscope repair w/ Helium reclamation.
    - Facilitate long tube work articles.



## ARC – Current Design status

#### Order of operations

- 1. Work article is introduced to 5-Axis Machining cell for preliminary inspection and pre-machining.
- 2. Work article translates to Antechamber.
- 3. Ante-chamber purges Oxygen.
- 4. Work article translates to Main seal chamber.
- 5. Cold spray operation begins on work article.
- 6. Work article translates back to 5-Axis Machining cell through Antechamber.
- 7. 5-Axis Machining cell conducts machining operations required on work article.
- 8. Work article is inspected and ready for removal.



#### 5-Axis Machining center

- Use and application of 5-Axis Machining center is heavily driven by product requirements.
- For current ARC concept, 5-Axis Machining center must have the following capabilities:
  - Positional tolerance of +/-0.0005"
  - Simultaneous axis synchronization
  - Work envelope of 36" Ø x 20" height
  - Part scanning capability
  - Work article automation
  - Automatic tool changer

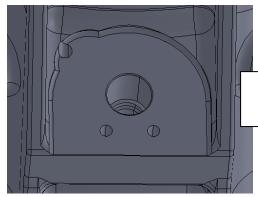




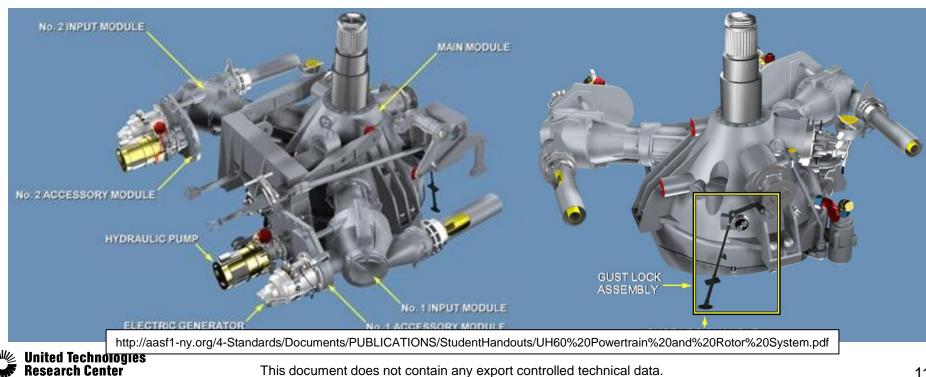
#### 5-Axis Machining center scanning



http://iteg.ncms.org/wp-content/gallery/ColdSpray/ColdSpray\_SlideDeck.pdf

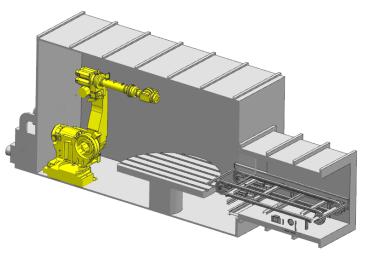


Compared to nominal geometry



#### Main Sealed Chamber

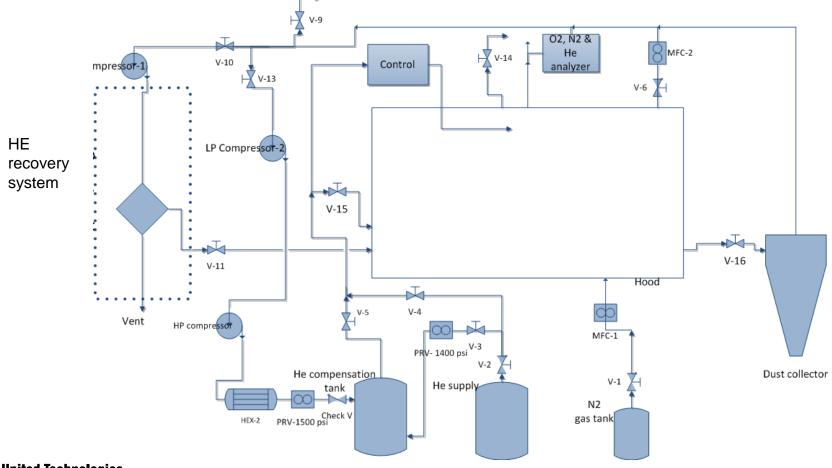
- Purpose to contain Helium used as propellant as work article undergoes coldspray operation.
- For current ARC concept, the Main Sealed Chamber must have the following features:
  - Internal volume of < 1000ft<sup>3</sup>
  - Vacuum rated door
  - Hermetic feedthroughs for robot and electrical wiring
  - Rotary table
  - Servo controlled pallet system
  - Operator glove box





#### Helium Reclamation System

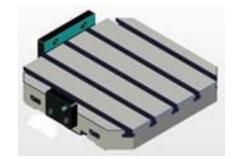
 Purpose to contain Helium used as propellant as work article undergoes cold spray operation.



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#### **Automation Solutions**

- Automation maintains a high efficiency workflow and repeatability. Degree of automation can be tailored to system requirements.
- Work article fixtured to pallet.
- Pallet maintains work article positioning.
- Pallet system requires integration with Antechamber/Main sealed chamber.
- Pallet system is highly configurable.
- Automation solutions include the use of robots.







### Thank you.

